CBUS - A universal layout control system

Documentation
Schema files
Index to other public Wiki pages

Introduction

CBUS is a Layout Control System running on the ⓦ CAN (Controller Area Network). A brief description of the system and available kits can be found on our public webpages. cbus.php and cbus2.php

A complete description of CBUS including the full specification and implementation notes is contained in the 'Developer's Guide' which can be downloaded from

developer_6b.pdf

CBUS Documentation

This is the public view of CBUS and does not include MERG Technical Bulletins (TBs) or links to any other MERG Copyright material which is available only to members.

CBUS Developers' Guide
Commanding Accessory Decoders using CANCMD & JMRI

Tools:

- **FCU**: Windows based FLiM Configuration Utility for configuration of nodes and events.
- **JMRI**: Java Model Railroad Interface for configuration, monitoring and operating.
- **ROCRAIL**: A complete package for layout and loco operation.
- **SSI** (Solid State Interlocker) from GPPSOFT: A complete layout control system following British signalling and control practice.

- A complete description of CBUS including the full specification and implementation notes is contained in the 'Developer's Guide' which can be downloaded from
  developer_6b.pdf
  See also the 'documentation' link at the top of this page.

From:
https://www.merg.org.uk/merg_wiki/ - **Knowledgebase**

Permanent link:
https://www.merg.org.uk/merg_wiki/doku.php?id=public:cbuspublic:start&rev=1579707592

Last update: **2020/01/22 15:39**